

Diagnostic systems in DEMO: engineering design issues

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The diagnostic systems of DEMO that are mounted on or near the torus, whether intended for the monitoring and control functions of the engineering aspects or the physics behaviour of the machine, will have to be designed to suit the hostile nuclear environment. This will be necessary not just for their survival and correct functioning but also to satisfy the pertinent regulatory bodies, especially where any of them relate to machine protection or the prevention or mitigation of accidents relevant to human safety. This presentation aims to indicate the more important of the design considerations that are likely to apply to diagnostics for DEMO, drawn from experience on JET, the provisions in hand for ITER and modelling results for the neutron effects in DEMO.

JET is presently the nearest machine to DEMO that is in operation, while ITER is of course a vital intermediate step. JET is not subject to nuclear regulatory scrutiny but nevertheless operates under a rigorously applied safety case following the same principles as those developed for the fission plant that the JET Operator (the UK Atomic Energy Authority) once operated. Accordingly diagnostic systems mounted on the machine have to satisfy over twenty criteria, described in a JET design approval check-list. These design constraints and approvals necessary to get diagnostic systems implemented on JET are necessarily more onerous than those applied to other (non-DT) operating tokamaks. It should be noted that DT operation in JET involved a site inventory of only 20g of tritium, totalled about 3×10^{20} neutrons and resulted in torus radiation fields two weeks after shut-down of around 10mGy/hr, while for ITER the figures are 4kg, $\sim 3 \times 10^{27}$ neutrons and 500Gy/hr, and DEMO perhaps 6kg, $\sim 1.4 \times 10^{29}$ neutrons (in ~ 3 FPY) and about 10kGy/hr. The corresponding neutron damage, affecting components near the plasma, is in the region of 1.2×10^{-6} , 2 and 60 displacements per atom respectively. It can immediately be seen that as onerous as the JET design criteria might be, those of ITER and one day DEMO will be far more so.

The following should be amongst the considerations in the design of DEMO diagnostics:

real-time radiation-induced effects	avoidance of halogens (tritium plant poisons)
radiation damage (e.g. in mirrors and transparent optics)	impact on neutron fluxes elsewhere
remote handling compatibility (and fault-condition recovery)	earthing and signal paths
useful life between component replacements (if possible)	material transition welds
neutron streaming (labyrinths, line of sight restrictions)	RAMI
tritium and active dust confinement	EMI screening (source or recipient)
use of reduced-activation materials and coolants	ICRH and ECRH immunity
seismic and disruption acceleration forces	vignetting of other systems (photon, particle)
vibration and other operational cyclic loads	thermal environment including cycling
disruption-induced currents and voltages	UHV design principles
installation and operational clearances	fast particle impacts

In this light, it becomes clear that if it is essential to operate DEMO with finely structured plasma profiles in order to achieve adequate stability or fusion gain, it will be especially challenging to meet all the necessary design and implementation criteria for the associated high resolution and sophisticated plasma diagnostics. Ultimately, though, the degree of sophistication desired in measurement and control should be a question of overall whole-life cost, or perhaps the amortised cost of each unit of electricity sold to the utilities. Accordingly, the presentation will focus on some of the more demanding engineering design requirements.

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